# Data Structures and Compression Algorithms for Genomic Sequence Data 

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#### Abstract

Motivation: The continuing exponential accumulation of full genome data, including full diploid human genomes, creates new challenges not only for understanding genomic structure, function, and evolution, but also for the storage, navigation, and privacy of genomic data. Here we develop data structures and algorithms for the efficient storage of genomic and other sequence data that may also facilitate querying and protecting the data. Results: The general idea is to encode only the differences between a genome sequence and a reference sequence, using absolute or relative coordinates for the location of the differences. These locations and the corresponding differential variants can be encoded into binary strings using various entropy coding methods, from fixed codes such as Golomb and Elias codes, to variables codes, such as Huffman codes. We demonstrate the approach and various tradeoffs using highly variables human mitochondrial genome sequences as a testbed. With only a partial level of optimization, 3,615 genome sequences occupying 56 Megabytes in GenBank are compressed down to only 167 Kilobytes, achieving a 345 -fold compression rate, using the revised Cambridge Reference Sequence as the reference sequence. Using the consensus sequence as the reference sequence, the data can be stored using only 133 Kilobytes, corresponding to a 433 -fold level of compression, roughly a $23 \%$ improvement. Extensions to nuclear genomes and high-throughput sequencing data are discussed. Availability: Data is publicly available from GenBank, the HapMap Web site, and the MITOMAP database. Supplementary materials with additional results, statistics, and software implementations are available from http://mammag.web.uci.edu/bin/view/ Mitowiki/ProjectDNACompression.


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## 1 INTRODUCTION

As high-throughput genome sequencing technologies continue to improve, genome sequence data continue to accumulate at an exponential pace. Not only do we already have the genome sequence of thousands of viruses and bacteria and dozens of multicellular organisms from plants to humans, but we are rapidly approaching
the stage where sequencing individual diploid human genomes will be economically affordable. The first diploid human genome sequences were recently produced (Levy et al., 2007; Wheeler et al., 2008; Wang et al., 2008) and a project to sequence 1,000 human genomes in the next few years is under way (Kaiser, 2008). And so is the race for the capability to sequence an individual human genome for less than $\$ 1,000$ within a few years (Service, 2006). Millions of human genome sequences could be generated within a decade or two.

In addition to the obvious challenges to understand the structure, function, and evolution of genomes, modern high-throughput sequencing methods also raise questions about how to efficiently represent, store, transmit, query, and protect the privacy of sequence information. These questions are further reinforced if one takes into account also progress in synthetic biology and our ability to bioengineer new sequences.

Currently, publicly available genomes are typically stored as flat text files in GenBank, but this approach is unlikely to scale up in many ways. The storage of the diploid genomes of all currently living humans using this simple approach would take "GenBank", without counting headers or any additional annotations, on the order of $36 \times 10^{18}$ bytes, or 36 M Terabytes, an amount difficult to store or download over the Internet, even using standard compression technologies (e.g gzip). And even with the progress that can be expected with Moore's law for storage and networking in the coming years, it is likely that security and privacy issues will require additional layers of protection around genomic data.

Here we develop data structures and algorithms to begin addressing these problems. These data structures allow the compression of genome and other sequences while facilitating certain classes of sequence queries by bypassing classical sequence alignments and dynamic programming algorithms. The approach is demonstrated primarily using a benchmark dataset comprising a few thousand of individual mitochondrial genome sequences. Human mitochondrial sequences provide an excellent testbed for developing and testing efficient data structures and algorithms because, unlike nuclear genome sequences, many thousands of fully sequenced mitochondrial genomes are already available, from a diverse population of individuals. In addition, mitochondrial genome sequences pose unique challenges due to their greater

[^0]variability, as compared to SNP data, resulting from their higher mutation rates.

## 2 GENERAL APPROACH

In the case of multiple genomes from the same species, associated with "resequencing" technologies, the flat text file approach is clearly wasteful since for the most part the sequences are identical. Thus a simple approach is to store a reference sequence, and then for each other sequence, encode only the differences (or "deltas") with respect to the original sequence. More precisely, consider first the sequences AACGACTAGTAATTTG and CACGTCTAGTAATGTG which are identical, except for a substitution in position $1(A \rightarrow C)$, $5(\mathrm{~A} \rightarrow \mathrm{~T})$, and $14(\mathrm{~T} \rightarrow \mathrm{G})$. Each SNP can be encoded by a pair $(i, X)$, where $i$ is an integer encoding the position and $X$ represents the value of the substitution relative to the reference. Thus given the first sequence as a reference, the second one can be encoded by the string "1C5T14G", concatenating the coordinates of the locations at which the variations occur and the SNP values at these locations. Note that with this data representation, the questions "Is this sequence different from the reference sequence at position $i$ ? And if so how?" are easy to answer. Thus the same data structure that facilitates compact representation, facilitates also efficient information retrieval.
Other events such as deletions and insertions can easily be accommodated in the same general scheme. For a deletion, imagine using two integers $(i, l)$ where the first integer denotes the position where the deletion occurs, and the second integer represents the length of the deletion. Likewise, for an insertion of length $l$, one can use the encoding $i, X_{1} \ldots X_{l}$ to denote the insertion of $X_{1} \ldots X_{l}$ at position $i$ with respect to the reference sequence

Although the basic idea is easy to understand, and not new, a precise implementation requires addressing a number of important technical issues. A first observation is that one can use local relative addresses, i.e. intervals, rather than absolute addresses. Using intervals, the above example"1C5T14G" becomes "0C4T9G". With intervals the dynamic range of the integers to be encoded may be considerably smaller than with absolute addresses. The relatively modest price to pay is that intervals must be added to recover absolute coordinates.

A second observation is that if the positions at which variations occur in the population are fixed and form a relatively small subset of all possible positions, then additional savings may result by focusing only on those positions. If in the same schematic example as above, one knew that in the population substitutions can occur only at positions 1,5 , and 14 , then one could, for instance, encode "1C5T14G" simply by "CTG", at the cost of keeping an additional table storing the coordinates where the variants occur, and using the letter in the reference sequences at positions where the reference sequence and the sequence under consideration are identical. This approach could be suitable, for instance, for the SNP HapMap data (HapMap Consortium, 2003, 2007), but may not be suitable in other situations, where either the location of all possible variations occurring in the population under consideration is not known in advance, or the number of such locations is very large across the population, but not very large in a typical sequence. This is the case, for instance, of mitochondrial DNA which is characterized by much
higher mutation rates than nuclear DNA. Thus different situations may lead to different variations of the basic idea.

An additional technical consideration is the choice of the reference sequence. In particular, the reference sequence does not need to be an actual genome but can, for instance, correspond to a consensus genome. While the resequencing case is of primary interest here due to the medical implication associated with resequencing human genomes, the same general ideas can be applied also to the case of de novo sequencing by using, for instance, the genome of the closest available species as the reference genome.

However, no matter what the detailed scenario is, all applications of the basic ideas hinge on a fundamental technical problem: how encode integers, representing for instance absolute or relative genomic addresses or read lengths, into binary strings. It is essential to understand that the naive idea of converting integers to their binary value, that is converting a " 5 " to" 101 " does not work at all since with this encoding one does not know where an integer ends and the next one begins. There are no spaces, tabs, or commas available to separate consecutive integers in the ultimate binary format of any computer where only the symbols 0 and 1 are available. Thus the encoding itself must somehow contain the information necessary to uniquely determine the beginning and end of each information item. In addition, the plain conversion of integers to binary does not take into account any entropy considerations. similarly, a general purpose compression scheme for text data, such as Lempel- Ziv (gzip), is likely to be far from optimal for genome and HTS data. In short, we are interested in binary encoding schemes for sequences of integers that can be parsed automatically and that, consistently with information theory, are entropy efficient, in the sense that fewer bits are used to encode more frequent events. The goal here is not to prescribe a single strategy to achieve this end, but rather to present a family of related coding strategies and some of the tradeoffs that would have to be optimized in a practical application, and illustrate the approach using highly variable mitochondrial DNA.

## 3 SPECIFIC ENCODING STRATEGIES

To begin with, we illustrate these issues here by considering how the integer positions $i$ are ultimately encoded into a binary string. From Shannon's entropy coding theory (McEliece, 1977; Cover and Thomas, 1991), optimal encoding of these integers from a compression standpoint depends on their distribution in order to assign shorter binary codes to more probable symbols (integers). For simplicity, we distinguish two broad classes of codes: fixed codes, such as Golomb (Golomb, 1965) and Elias codes (Elias, 1975), and variable codes, such as Huffman codes (Huffman, 1952). In a fixed code, the integer $i$ is always encoded in the same way, whereas in a variable code the encoding changes.

### 3.1 Fixed Codes: Golomb and Golomb-Rice Codes

Both Golomb codes and Elias codes encode an integer $j$ by catenating two bit strings: a preamble $p(j)$, that encodes $j$ 's scale, and a mantissa. Golomb codes were specifically developed to encode stationary coin flips with $p \neq 0.5$. Thus they are known to be optimal and asymptotically approach the Shannon limit if the data is generated by random coin flips or, equivalently, if the distribution over the integers is geometric, although they can be used for any
other distribution. The more skewed the probability $p$ is (towards 0 or 1) the greater the level of compression that can be achieved.
Golomb codes have one integer parameter $m$. Given $m$, any positive integer $j$ can be written using its quotient and remainder modulo $m$ as $j=\lfloor j / m\rfloor+(j \bmod m)$. To encode $j$, the Golomb code with parameter $m$ (Table 1) encodes the quotient and remainder by using:

- $\lfloor j / m\rfloor 1$-bits for the quotient;
- followed by a 0 , as a delimiter (unary encoding of $\lfloor j / m\rfloor$ );
- followed by the phased-in binary code for $j \bmod m$ for the remainder (described below).

The encoding of integers $0, \ldots, m-1$ normally requires $B=$ $\lceil\log m\rceil$ bits. If $m$ is not a power of two, then one can sometimes use $B-1$ bits. More specifically, in the "phased-in" approach:

- if $i<2^{B}-m$, then encode $i$ in binary, using $(B-1)$ bits;
- if $i \geq 2^{B}-m$, then encode $i$ by $i+2^{B}-m$ in binary, using $B$ bits.

For instance, for $m=5, i=2$ is encoded as " 10 " using $2(=B-1)$ bits, and $i=4$ is encode as " 111 " using $3(=B)$ bits (see Table 1 ). Thus the encoding of $j$ requires in total $\lfloor j / m\rfloor+1+\lfloor\log m\rfloor$ or $\lfloor j / m\rfloor+1+\lceil\log m\rceil$ bits (Table 1) and the codeword for the integer $j+m$ has one more bit than the codeword for the integer $j$. Unless otherwise specified, all logarithms are taken to base 2 . We use also " $[\log m]$ " to denote " $\lfloor\log m\rfloor$ or $\lceil\log m\rceil$ ".

| $j$ | $m=2$ | $m=3$ | $m=4$ | $m=5$ | $m=6$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 00 | 00 | 000 | 000 | 000 |
| 1 | 01 | 010 | 001 | 001 | 001 |
| 2 | 100 | 011 | 010 | 010 | 0100 |
| 3 | 101 | 100 | 011 | 0110 | 0101 |
| 4 | 1100 | 1010 | 1000 | 0111 | 0110 |
| 5 | 1101 | 1011 | 1001 | 1000 | 0111 |
| 6 | 11100 | 1100 | 1010 | 1001 | 1000 |
| 7 | 11101 | 11010 | 1011 | 1010 | 1001 |
| 8 | 1111100 | 11011 | 11000 | 10110 | 10100 |

Table 1. Golomb encoding of the integers $j=0$ to 8 , for different values of the parameter $m$.

The entropy of the geometric distribution of the coin flip runlengths is given by (using $q=1-p$ ):

$$
\begin{equation*}
H(\text { geometric })=-\sum_{j=0}^{\infty} q^{j} p \log \left(q^{j} p\right) \tag{1}
\end{equation*}
$$

and provides the optimal Shannon coding lower bound on the expected encoding length $l$ per integer

$$
\begin{equation*}
E(l) \approx \sum_{j=0}^{\infty} q^{j} p(\lfloor j / m\rfloor+1+[\log m]) \tag{2}
\end{equation*}
$$

| Number | Encoding $(k=2)$ | Number | Encoding $(k=3)$ |
| :---: | :---: | :---: | :---: |
| $0-3$ | 0 xx | $0-7$ | 0 xxx |
| $4-7$ | 10 xx | $8-15$ | 10 xxx |
| $8-11$ | 110 xx | $16-31$ | 110 xxx |
| 33 | 11111111001 | 33 | 11110001 |

Table 2. Golomb-Rice encoding of integers $j=0-33$ with $k=2$ ( $m=$ 4) and $k=3(m=8)$. Integer $j$ is encoded by concatenating $\left\lfloor j / 2^{k}\right\rfloor 1$-bits, one 0 -bit, and the $k$ least significant bits of $j$.

| Number | Encoding |
| :--- | :---: |
| 1 | 1 |
| $2-3$ | 01 x |
| $4-7$ | 001 xx |
| $8-15$ | 0001 xxx |
| $16-31$ | 00001 xxxx |

Table 3. Elias Gamma encoding. Each integer $j$ is encoded by concatenating $\lfloor\log j\rfloor 0$ 's with the binary value of $j$.
under the coin flip model. Thus the Golomb code approaches the Shannon limit when $q^{m}=0.5$. In particular, this ensures that for each integer $j$

$$
\begin{equation*}
-\log P(j)=\log \left(q^{j} p\right) \approx\lfloor j / m\rfloor+1+[\log m] \tag{3}
\end{equation*}
$$

where $P(j)$ is the probability associated with the integer $j$.
Finally, Golomb-Rice codes are a particularly convenient subfamily of Golomb codes, when $m=2^{k}$ (Table 2). To encode $j$, we concatenate $\left\lfloor j / 2^{k}\right\rfloor 1$-bits, one 0 -bit, and the $k$ least significant bits of $j$. The length of the encoding of $j$ is thus $\left\lceil j / 2^{k}\right\rceil+k+1$. The decoding of Golomb-Rice codes is particularly simple, the position of the 0 -bit gives the value of the prefix to be followed by the next $k$ bits.

### 3.2 Elias Codes

In the Elias Gamma coding scheme, the preamble $p(m)$ is a string of zeroes of length $\lfloor\log j\rfloor$, and the mantissa $m(j)$ is the binary encoding of $j$. More precisely, to encode the scale and value of $j$ :

- write $\lfloor\log j\rfloor 0$-bits;
- followed by the binary value of $j$ beginning with its most significant 1-bit.

The length of the encoding of $j$ is $2\lfloor\log j\rfloor+1$ (Table 3). The decoding is obvious: first read $n 0$-bits until the first 1 -bit is encountered, then read $n$ more bits to get the binary representation of $j$.

Applying the relationship

$$
\begin{equation*}
-\log P(j) \approx 2\lfloor\log j\rfloor+1 \tag{4}
\end{equation*}
$$

to the integer probabilities, shows that Elias Gamma encoding asymptotically approaches the Shannon limit for $P(j) \approx C j^{-2}$. This is a power law relationship with exponent -2 and $C$ is a normalizing constant. Note that for both Golomb (Equation 3) and Elias Gamma codes (Equation 4), several different consecutive
integers can be encoded into a bit vector with the same length, hence the relationships $-\log P(j) \approx$ length $(j)$ is only approximate with respect to geometric or power-law distributions over the integers. To be more precise, the optimal distribution associated with the Elias Gamma code can be separated into the product of a probability distribution over the length $l$ given by $P(l)=2^{-l}$ and a uniform distribution over the integers having an encoding of length $l$ given by $P(j \mid l)=2^{-l+1}$.
More recently, new families of efficient fixed codes for integers have been developed (Moffat and Stuiver, 2000; Moffat and Anh, 2006; Baldi et al., 2007; Hirschberg and Baldi, 2008), for instance in the case of increasing or quasi increasing sequences of integers, by encoding only the deltas of the preambles. For sequence data, the absolute addresses are increasing, and the relative addresses could be made quasi-increasing if one were to apply a fixed permutation to all the sequences to be stored, at the cost of storing and using this permutation (Baldi et al., 2007).

### 3.3 Decoding and Byte Arithmetic

While the degree of compression achieved is an important criteria, the complexity and speed of decoding is also important in all the applications to be considered. For all the encoding algorithms described above, we have also described corresponding simple and fast decoding algorithms. Direct implementations of the decoding algorithms process the compressed representations bit-bybit; however, it is possible to implement even faster decoders, which decode the compressed data byte-by- byte. These faster decoders work by looking up information from pre-computed tables. These tables are indexed by: (1) all possible bytes B (ranging from 0 to 255 ); and (2) a bit-index i (ranging from 0 to 7 ) which marks the position of the decoder within the byte. These tables may store quantities such as the binary value of byte B starting from bit i , the number of bits turned on in byte B starting from bit i , and the unary value of byte B starting from bit i . The exact quantities stored depend on the details of a particular decoder implementation. In practice, byte arithmetic considerably increases decoding speed, sometimes approaching as much as an eight-fold improvement over the corresponding bit-by-bit implementation. The exact value of the speedup depends on several factors including the characteristic of the data, the exact compression scheme, and the hardware used.

### 3.4 Variable Codes

In genomic applications, in general the integers may not have a well defined distribution, in which case it is always possible to use a general entropy encoding scheme, such as Huffman coding (Huffman, 1952; McEliece, 1977; Cover and Thomas, 1991) which essentially builds a prefix code by using a binary hierarchical clustering algorithm starting from the events (integers) with the lowest probability. While Huffman coding achieves compression close to the entropy limit, the price to pay over fixed coding schemes such as Golomb and Elias Gamma, or the more recent codes mentioned above, is the storage of the Huffman table which can be quite large in some applications. However this is a fixed cost with respect to the database size, and therefore whether this cost is acceptable or not depends on the specific application. Small gains in compression over Huffman coding may be obtained using arithmetic coding (Rissanen and Langdonr, 1979; Witten et al., 1987), but at a non-trivial price in the complexity of computations.

## 4 RESULTS

### 4.1 Data Extraction

To demonstrate the general approach, 3,615 human mitochondrial sequences were downloaded from a recent version of GenBank. We focused on the sequences alone, ignoring any header and any other exogenous information. We first use the the Revised Cambridge Reference Sequence (rCRS) sequence (GenBank accession number: AC_000021) as the reference sequence (Brandon et al., 2005; Ruiz-Pesini et al., 2007). The reference sequence is $16,568 \mathrm{bp}$ long. Among the other sequences, 2,671 correspond to complete genomes, while the remaining 944 correspond only to the coding region sequence, which is about $\sim 1,100 \mathrm{bp}$ shorter than the full genome sequence, and extends from position 577 to 16,023 of the reference sequence. 80 sequences contained ambiguous symbols which, for simplicity, were replaced by the corresponding value in the reference sequence. This replacement is without much loss of generality since ambiguous symbols could easily be accommodated into the coding schemes, for instance as additional variation types.


Fig. 1. Distribution of intervals between variations using a $\log$ rank-log frequency plot. $x$-axis represents the logarithm of the rank associated with decreasing interval frequencies. $y$ axis represents the logarithm of the corresponding counts.

### 4.2 General Statistics

There are 4,577 positions along the reference sequence where at least one of the other sequence deviates from the reference. In aggregate, there are $122,131 \mathrm{bp}$ that deviate from the reference sequence. Besides substitutions, the total number of insertion and deletion events across all the sequences is 7,119 , the most frequent one being 1 bp insertions (4,615 occurrences), followed by 2 bp deletions (901). Some well known variants, such as the "Asianspecific 9 bp deletion" (Harihara et al., 1992; Thomas et al., 1998), also occur frequently ( 255 occurrences). In total, there are 43 different kinds of variation events (see Tables 6 and 7). On average, a given sequence deviates from the reference sequence in 33.8 bp

|  | Intervals |  |  | Variants |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Huffman | Golomb | Elias Gamma | Huffman | Golomb | Elias Gamma |
| Cambridge | 9.21 | 11.10 | 12.93 | 2.66 | 2.44 | 2.77 |
| Consensus | 9.75 | 12.03 | 13.86 | 2.44 | 2.59 | 2.97 |

Table 4. Comparison of the average bit cost of encoding intervals and events for Huffman, Golomb, and Elias Gamma encoding schemes using the revised Cambridge Reference Sequence and the consensus sequence.

## Simplified mtDNA lineages



Fig. 2. Simplified Haplotype classification used in Brandon et al. (2009). rCRS $=$ revised Cambridge Reference Sequence.
with a standard deviation of 13.43 bp . The average number of substitutions (transition/transversions) per sequence is 30.69 bp . The average number of insertions per sequence is 1.69 bp , the average number of deletions is 1.37 bp .

The distribution of the raw intervals using the rCRS as the reference sequence is represented in Figure 1 displaying the logarithm of the counts versus the logarithm of the rank (in decreasing order of frequency). Observed intervals vary from 0 to $14,997 \mathrm{bp}$, the most frequent one being an interval of $72(2,579$ occurrences) (see interpretation in next section), followed by 687 (2,418 occurrences), and followed by 5 (2,130 occurrences). Overall this distribution is not strongly structured.

|  | H+H | G+G | E+E |
| :---: | :---: | :---: | :---: |
| Cambridge | $167(345)$ | $195(295)$ | $226(254)$ |
| Consensus | $133(433)$ | $159(361)$ | $183(314)$ |

Table 5. Total file size comparison using the rRCS and the consensus sequence, with Huffman encoding for both intervals and variants $(\mathrm{H}+\mathrm{H})$, or Golomb encoding for both interval and variants (G+G), or Elias Gamma encoding for both interval and variants ( $\mathrm{E}+\mathrm{E}$ ). Numbers are given in Kilobytes ( $1024 \times 8$ bits). In comparison, the raw data takes 56 Megabytes (57439.05 Kilobytes). Compression factor are given in parenthesis.

Table 6. Huffman encoding for the event types using the revised Cambridge Reference Sequence.

| variant | count | binary code |
| :--- | ---: | :--- |
| G | 42839 | 11 |
| C | 24753 | 01 |
| T | 22345 | 00 |
| A | 21003 | 101 |
| InsC | 3980 | 1001 |
| Del2bp | 901 | 100011 |
| Del1bp | 757 | 100001 |
| InsCC | 360 | 1000100 |
| InsT | 313 | 1000001 |
| Del9bp | 255 | 1000000 |
| InsA | 222 | 10001011 |
| InsCCC | 34 | 1000101000 |
| InsCCCC | 30 | 10001010110 |
| InsG | 29 | 10001010100 |
| InsCCCCC | 16 | 100010101110 |
| InsACA | 15 | 100010101011 |
| InsCCCCCC | 12 | 100010100110 |
| InsCCCCCCC | 8 | 1000101010101 |
| InsAC | 6 | 1000101001011 |
| InsCCT | 5 | 1000101001010 |
| Del6bp | 4 | 10001010111100 |
| Del8bp | 4 | 10001010111101 |
| InsCCCCCTCTA | 3 | 10001010011111 |
| Del3bp | 3 | 10001010101001 |
| InsGC | 1 | 1000101011111111 |
| InsCCCCCCCC | 3 | 10001010011101 |
| InsTT | 3 | 10001010101000 |
| Del4bp | 3 | 10001010011110 |
| InsACAC | 3 | 10001010011100 |
| InsACACA | 2 | 100010101111100 |
| InsCCCCCCCCC | 1 | 100010100100000 |
| InsTA | 1 | 100010100100111 |
| InsGA | 1 | 1000101011111110 |
| InsGG | 1 | 1000101011111101 |
| InsCA | 1 | 1000101011111100 |
| InsAG | 1 | 1000101011111011 |
| InsGATCACAG | 1 | 1000101011111010 |
| Del10bp | 1 | 100010100100011 |
| InsTCTCTGTTCTTTCAT | 1 | 100010100100010 |
| InsACACAC | 1 | 100010100100001 |
| InsAGAA | 1 | 100010100100101 |
| InsCACA | 1 | 1000100100100 |
| Del5bp | 1 |  |
|  |  |  |

Deletions (Del) are followed by their length. Insertions (Ins) by their content.

Table 7. Huffman encoding for the event types using the consensus sequence.

|  |  |  |
| :--- | ---: | :--- |
| variant | count | binary code |
| C | 26164 | 11 |
| A | 19576 | 01 |
| G | 18002 | 00 |
| T | 16528 | 101 |
| InsC | 3980 | 1001 |
| Del2bp | 901 | 100011 |
| Del1bp | 757 | 100001 |
| InsCC | 360 | 1000100 |
| InsT | 313 | 1000001 |
| Del9bp | 255 | 1000000 |
| InsA | 222 | 10001011 |
| InsCCC | 34 | 1000101000 |
| InsCCCC | 30 | 10001010110 |
| InsG | 29 | 10001010100 |
| InsCCCCC | 16 | 100010101110 |
| InsACA | 15 | 100010101011 |
| InsCCCCCC | 12 | 100010100110 |
| InsCCCCCCC | 8 | 1000101010101 |
| InsAC | 6 | 1000101001011 |
| InsCCT | 5 | 1000101001010 |
| Del6bp | 4 | 10001010111100 |
| Del8bp | 4 | 10001010111101 |
| InsCCCCCTCTA | 3 | 10001010011111 |
| Del3bp | 3 | 10001010101001 |
| InsGC | 1 | 100010100100100 |
| InsCCCCCCCC | 3 | 10001010011101 |
| InsTT | 3 | 10001010101000 |
| Del4bp | 3 | 10001010011110 |
| InsACAC | 3 | 10001010011100 |
| InsACACA | 2 | 10001010111100 |
| InsCCCCCCCCC | 1 | 100010100100000 |
| InsTA | 1 | 100010100100111 |
| InsGA | 1 | 100010101111110 |
| InsGG | 1 | 1000101011111101 |
| InsCA | 1 | 1000101011111100 |
| InsAG | 1 | 100010101111011 |
| InsGATCACAG | 1 | 1000101011111010 |
| Del10bp | 1 | 100010100100011 |
| InsTCTCTGTTCTTTCAT | 1 | 1000010100100010 |
| InsACACAC | 100010100100001 |  |
| InsAGAA |  |  |
| InsCACA | Del5bp |  |
|  | 10010011 |  |
|  |  |  |

Deletions (Del) are followed by their length. Insertions (Ins) by their content.

### 4.3 Changing the Reference Sequence

There are no particular reasons, beyond standardization and tradition, for using rRCS as the reference sequence. Furthermore, purely from a compression standpoint, the rCRS may not be optimal due to biases in data. To illustrate this point we computed the haplotype distribution of the data using the simplified haplotype classification described in Figure 2 (see also (Brandon et al., 2009; Mishmar et al., 2003)). We find the following skewed distribution: $11.2 \%$ African ( 405 sequences), $26.3 \%$ Asian ( 950 sequences), and
62.5\% EurAsian (2,260 sequences). In addition, it is well known that the original Cambridge Reference sequence contains a number of errors and has been revised over the years (Anderson et al., 1981; Andrews et al., 1999) (The revisions to the original sequence are described at: http://www.mitomap.org/mitoseq.html). This alone, for instance, explains why the interval 72 is so frequent with respect to the rCRS: the rCRS sequence has a G in the corresponding position, which is a very rare variant, most likely an error.

Thus it is clear that other reference sequences could be used to improve compression rates and minimize the total number of variants. Furthermore, the reference sequence does not need to be a sequence from an actual individual, but could be designed using purely statistical considerations. Note that the design of the reference sequence impacts not only the variants to be recorded, but also the intervals, and therefore it must also take into consideration any constraints a particular implementation may place on the intervals and their encodings. A reasonable choice adopted here to try to further improve the compression rate, is to use the consensus sequence, derived by computing the consensus at each position, as the reference sequence.

Using the consensus sequence, observed intervals vary from 0 to $11,717 \mathrm{bp}$, the most frequent one being an interval of $5(2,104$ occurrences), followed by 1 ( 1,251 occurrences), and followed by 259 ( 895 occurrences).

### 4.4 Encoding and Compression

We explored and compared different encoding schemes using both fixed and variable codes. The main sample of results is given in Tables 4 and 5 giving the average number of bits required to encode an interval or a variant, using Huffman, Golomb, or Elias Gamma codes, with the rCRS or the consensus sequence, as well as the total number of bits required to encode the entire data. The Huffman coding tables for the events are given in Tables 6 and 7 for the rCRS and consensus sequence respectively.

As can be seen in Table 5, Huffman coding achieves slightly better compression rates than Golomb or Elias Gamma coding, with a table storage cost that may be manageable in this case. The raw data takes 56 Megabyte ( $58,817,584$ bytes) of space. By concatenating the Huffman codes for the intervals and the variants $(\mathrm{H}+\mathrm{H})$, the encoded data requires only 167 Kilobytes of space, corresponding to a 345 -fold level of compression. Using, for instance, Golomb codes for both the intervals and the variants ( $\mathrm{G}+\mathrm{G}$ ) requires instead 195 Kilobytes. The choice of the reference sequence has a noticeable effect. Although the average number of bits required to encode an interval or a variant is slightly higher for the consensus sequence (Table 4), this is compensated by a considerable decrease in the total number of variants to be encoded. This is true here even with a consensus sequence that differs from the rRCS sequence by only 11 nucleotides. As shown in Table 5, the same encoding method based on using two Huffman codes ( $\mathrm{H}+\mathrm{H}$ ), applied with the consensus sequence, requires only 133 Kilobytes to store the entire data. This corresponds to a 433 -fold level of compression, roughly a $23 \%$ improvement.

## 5 DISCUSSION

A simple but general data structure and data encoding approach has been developed for the efficient storage of genomic data.

| Encoding | DataSet 1 | DataSet 2 | DataSet 3 |
| :---: | :---: | :---: | :---: |
| Raw Sequence | $133,366,560$ | $353,182,128$ | $8,869,613,600$ |
| Flat File | $75,525,168$ | $185,536,864$ | $8,396,646,344$ |
| Elias Gamma Absolute | $358,402(210.73)$ | $79,281,140(2.34)$ | $1,373,892,116(6.11)$ |
| Elias Gamma Relative | $185,542(407.05)$ | $27,741,238(\mathbf{6 . 6 9})$ | $340,764,564(\mathbf{2 4 . 6 4})$ |
| Monotone Value (MOV) | $169,664(\mathbf{4 4 5 . 1 5 )}$ | $39,528,754(4.69)$ | $834,672,652(10.06)$ |

Table 8. Compression of the read addresses information from three HTS experiments (see text). The size in bits for the raw sequence data, the corresponding flat text file format for the corresponding addresses, and the compressed files for different compression algorithms. Elias Gamma coding is applied both to the absolute and relative addresses. Compression factors with respect to the flat text file format are given in parentheses, with top compression factors in bold. MOV is a coding algorithm specifically designed for increasing sequences of integers described in Baldi et al. (2007).

The approach specifically leverages homology between sequences and is different from general compression algorithms for text, or compression algorithms for single genome data (Williams and Zobel, 1997; Chen et al., 2002; Behzadi and Fessant, 2005). The approach has been demonstrated on the mitochondrial genomes, where it leads to 2-3 orders of magnitude improvement in data storage. From these compact representations, full sequences can be recovered rapidly using the reference sequence. Furthermore, queries regarding the existence and nature of variants at particular coordinate positions, such as those arising in a variety of applications from medicine to forensics, can be answered efficiently. Additional encryption methods may be applied to these representations to protect the security of both the genomic data and the queries.
The approach has been used for lossless compression, however it could be used also in lossy compression, for instance by ignoring variants that are not medically relevant. The approach is also applicable to other kinds of sequences, such as RNA or protein sequences. While for demonstration purposes we have used a single reference sequence, it is clear that one could cluster the data and use different reference sequences for different subgroups. In the case of mitochondria genomes, for instance, Figure 2 would suggest using at least three different reference sequences. Whether the gain in compression that can be expected for each subgroup, akin to the gain achieved by going from the rCRS to the consensus sequence, is worth the cost of having multiple reference sequences rather than a single one, cannot be answered in generality and depends on the details of a particular application, the number of genomes to be stored coming from each group, and so forth. For future work, the same idea of multiple reference sequences can be extended beyond the storage of genomes within a given species, to the storage of genomes from multiple species by using a phylogenetic hierarchy of reference sequences.

Finally, the approach can be extended to human nuclear genomes and to high-throughput sequencing (HTS) from different technologies and different kinds of experiments. For human SNP variation, data and statistics are readily available (Hinds et al., 2005; Goldstein and Cavalleri, 2005; HapMap Consortium, 2007). A comprehensive list of human SNPs is available from the dbSNP database maintained by NCBI. The current release (version 129) contains about 15 million SNPs. This data can readily be compressed using the techniques described here and additional gains in compression can be achieved by storing separately a fixed table recording the location of all the SNPs and leveraging the
skewed distribution of some of the SNP variants. In preliminary experiments, we have achieved compression factors of over 1,000 on the raw HapMap sequence data. Although SNPs account for most of genetic variation events between individuals, a much larger fraction of the genome (in terms of the total number of bases) is involved in larger structural variation events, such as copy number variations (CNV). While there have been studies attempting to derive a preliminary assessment of large-scale genomic complexity and variation (Feschotte and Pritham, 2007; Tuzun et al., 2005), statistics on the frequencies and location of these more complex structural variations in the human genome are still at an earlier stage of development. For instance, comparative analysis of the single diploid genome described in (Levy et al., 2007) "revealed more than 4.1 million DNA variants, encompassing 12.3 Mb . These variants (of which $1,288,319$ were novel) included 3,213,401 single nucleotide polymorphisms (SNPs), 53,823 block substitutions ( 2206 bp ), 292,102 heterozygous insertion/deletion events (indels)( 1571 bp ), 559,473 homozygous indels ( $182,711 \mathrm{bp}$ ), 90 inversions, as well as numerous segmental duplications and copy number variation regions. Non-SNP DNA variation accounts for $22 \%$ of all events identified in the donor, however they involve $74 \%$ of all variant bases. This suggests an important role for nonSNP genetic alterations in defining the diploid genome structure." A better statistical understanding of the coding constraints posed by these complex events, and how to encode them, should become possible as more full human genome sequences become available in the coming years (www. 1000 genomes.org).

Regarding HTS data, for illustration purposes here we consider the problem of storing the genomic addresses of the reads from three HTS datasets associated with different HTS technologies. The first data set is obtained from the laboratory of Dr. S. Sandmeyer at UCI and comes from an experiment aimed at mapping retrotransposon Ty3 insertion sites in the yeast genome. It consists of 833,541 sequence reads, all of length 19 bp . The second data set comes from a chromatin immunoprecipitation assay (ChIP-Seq) used to map the in vivo binding site locations of the neuron-restrictive silencer factor (NRSF) in humans (Johnson et al., 2007). It consists of 1,697,991 sequence reads, all of length 25 bp and mapped to the most recent human genome sequence (hg18). The third data set corresponds to a full diploid human genome sequencing experiment for an Asian individual (Wang et al., 2008). This is a very large data set with enough reads to provide 36 -fold average coverage, and we utilize the existing mapping of the reads provided by the YH database (Li et al., 2009) to the human reference genome. For illustrative
purposes, we report only the results corresponding to the reads associated with chromosome 22 . For chromosome 22, there are $31,118,532$ reads that vary in length from 30 to 40 bp for a total of $1,108,701,700 \mathrm{bp}$ of sequence data. While complete details of these experiments will be reported elsewhere, Table 8 shows the resulting compression factors which are again in the range of one to three orders of magnitude, depending on the statistical properties of the data sets. The same techniques described here can readily be applied to storing also the length of the reads, the content of the reads, where they differ from the reference genome, their quality, and so forth. Statistical properties of the reads and the underlying HTS technologies, e.g increasing error rates towards the end of the read, can also be exploited to achieve efficient compression. Thus the data structures and compression algorithms described here provide a framework for the management of HTS and genomic data that can be flexibly applied in different environments.

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